

FIG. 2a

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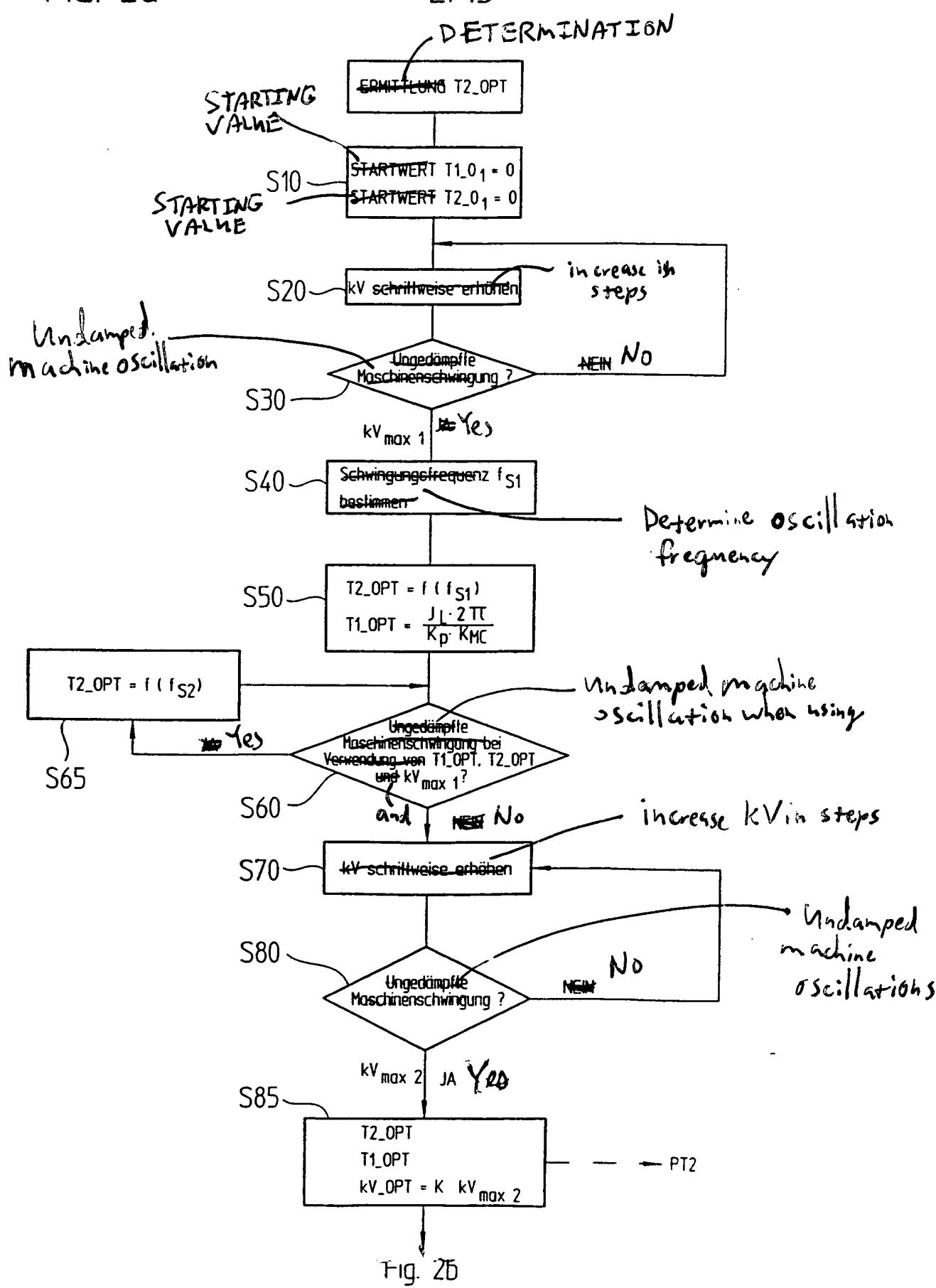


FIG. 2b

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Fig. 2a

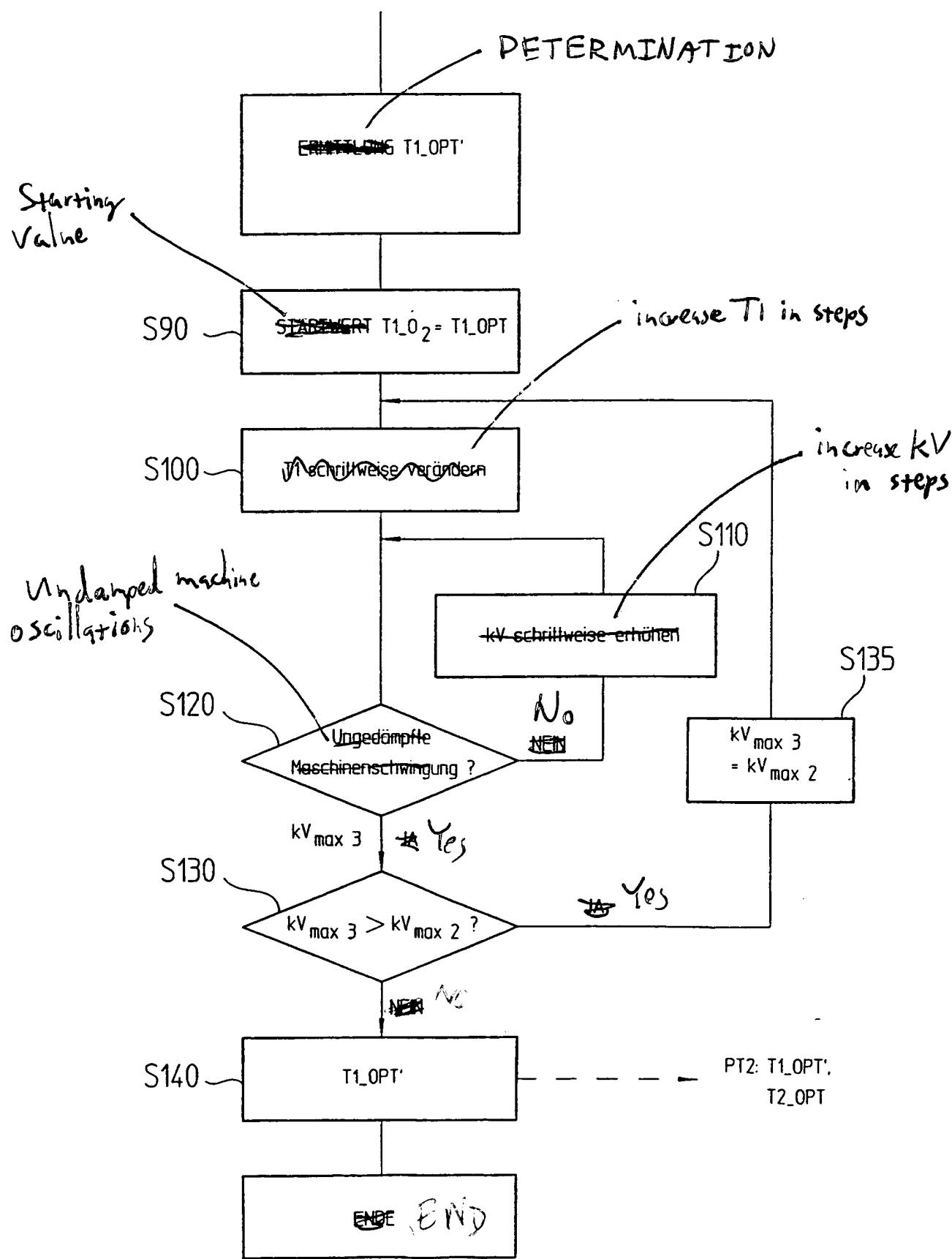


FIG. 3

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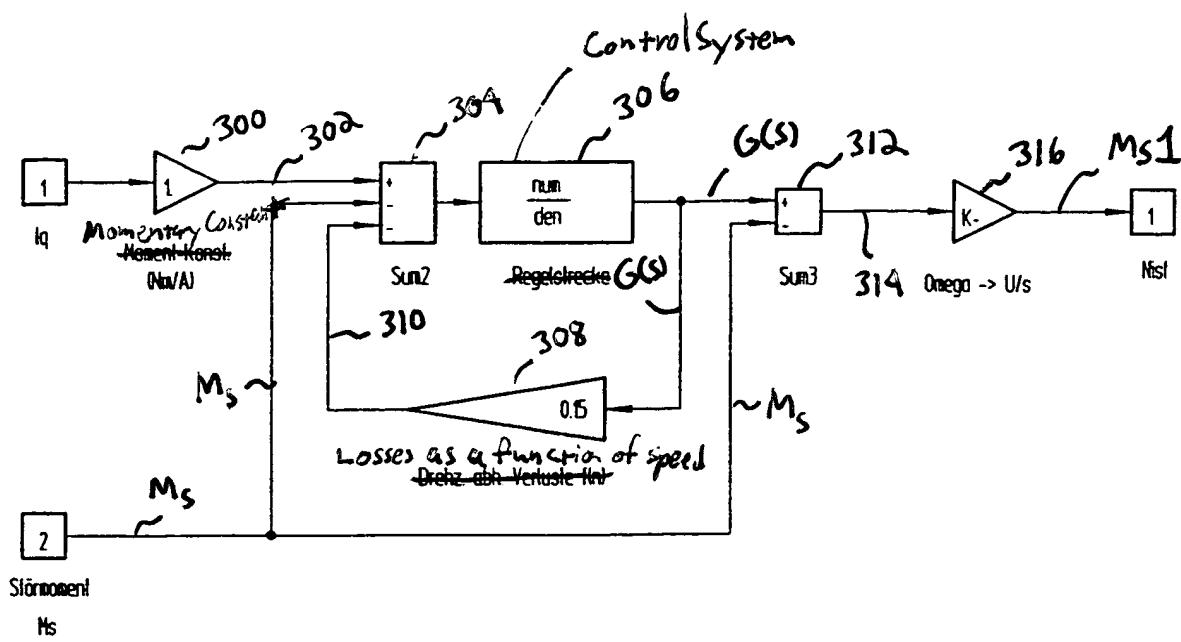


FIG. 4

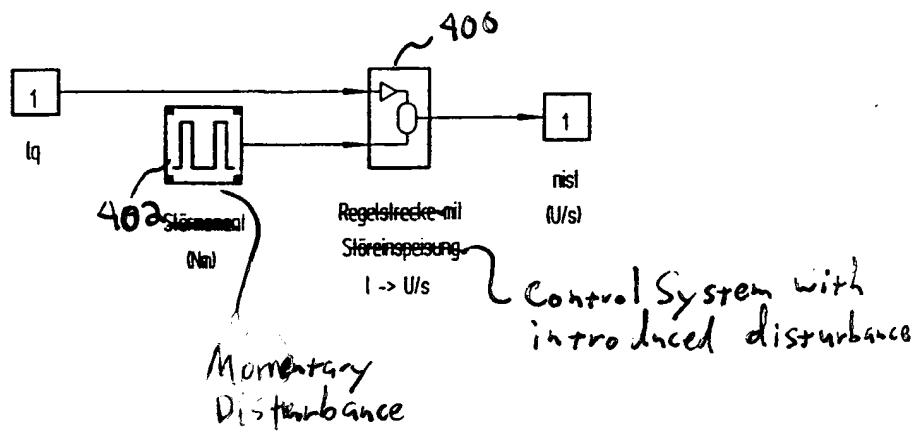
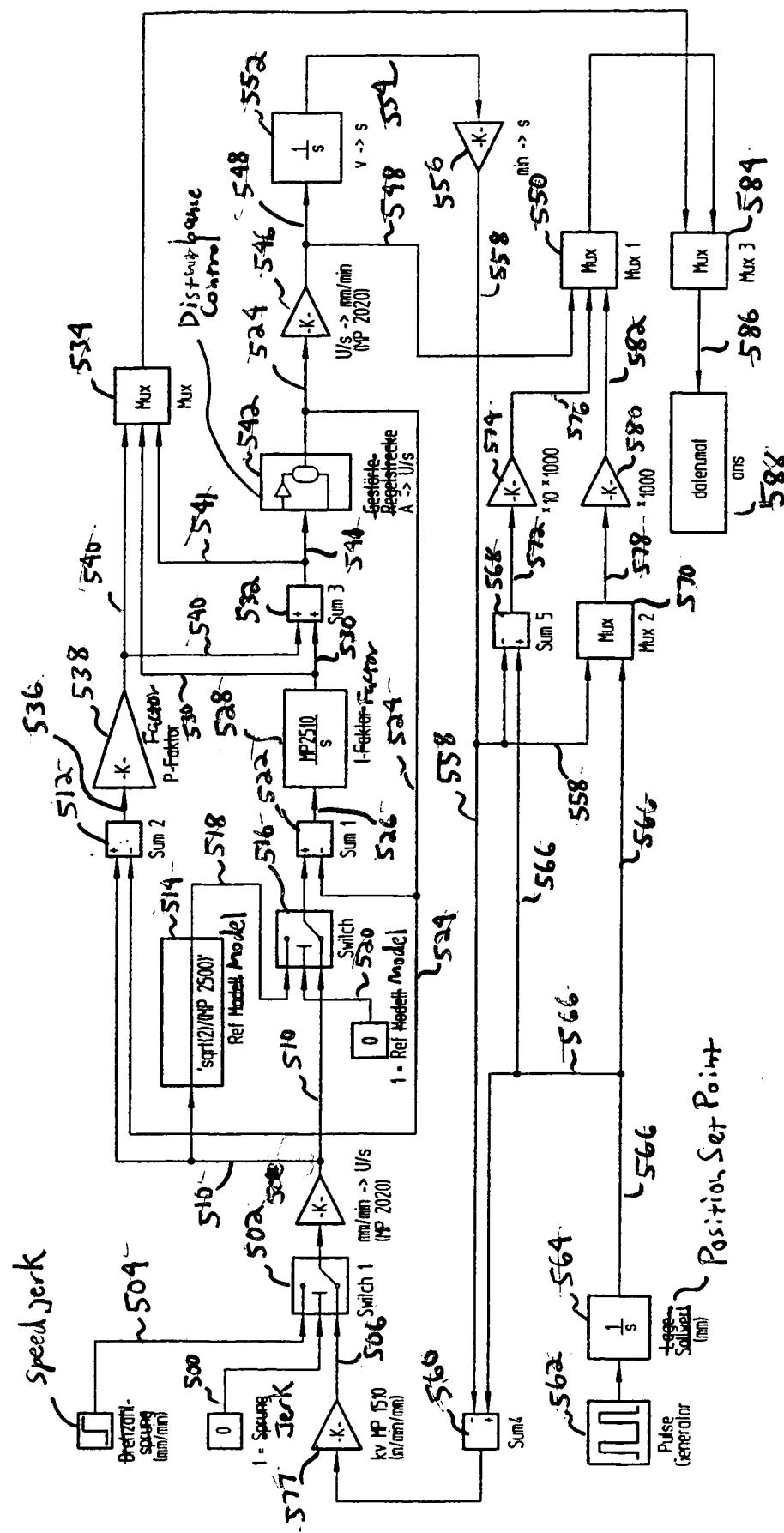


FIG. 5

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Fig. 6

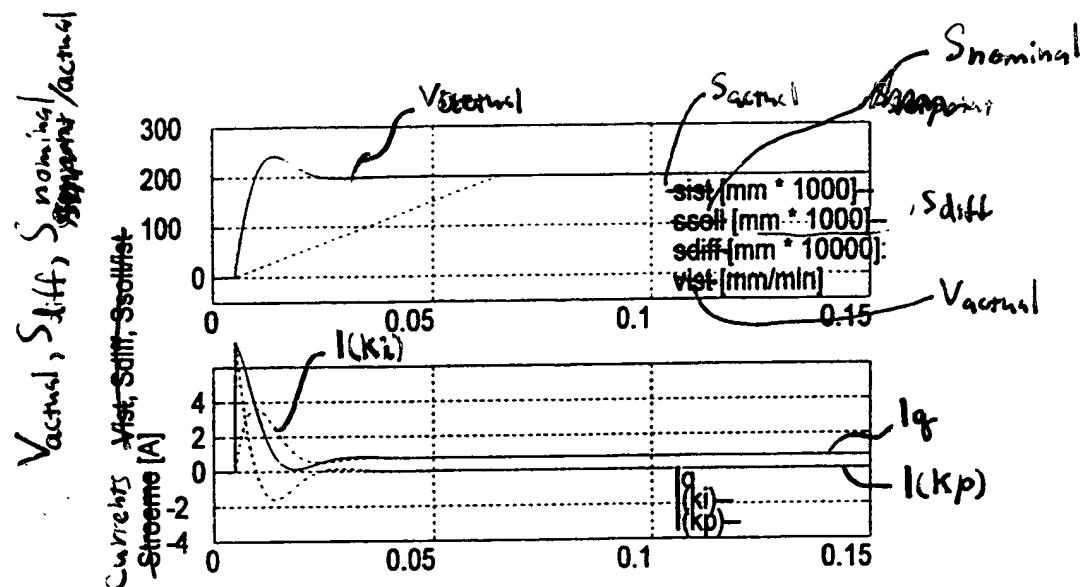
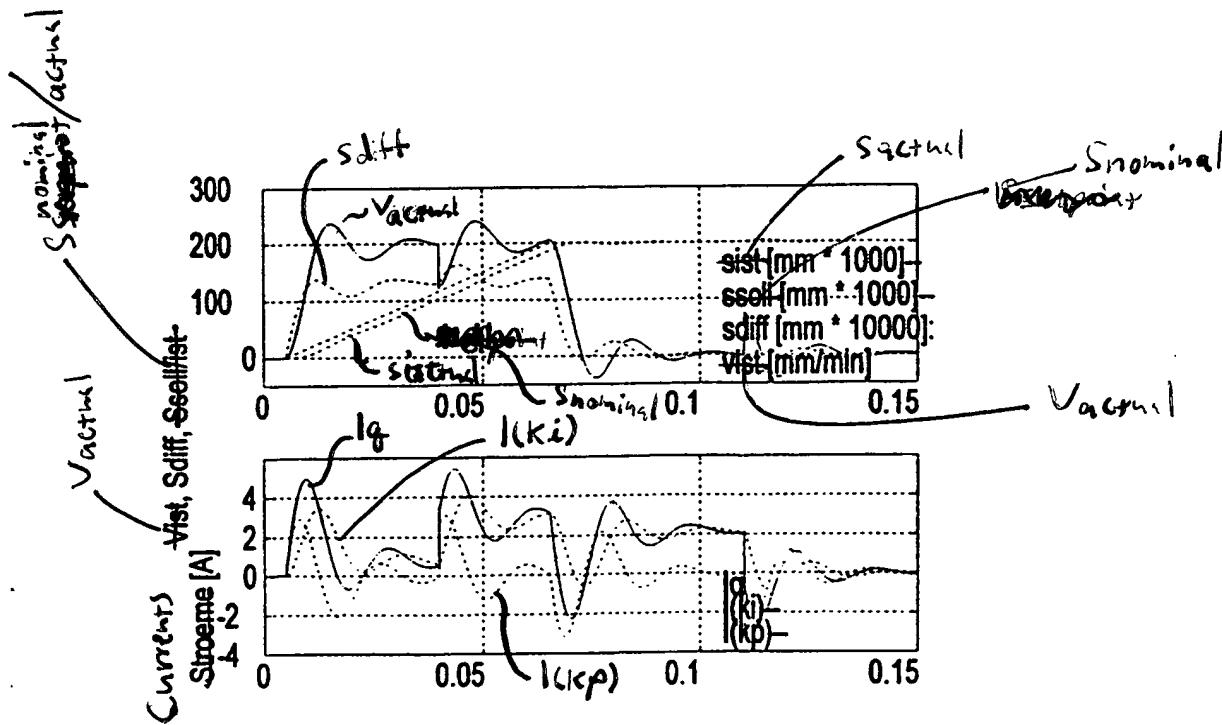


Fig. 7



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Fig. 8

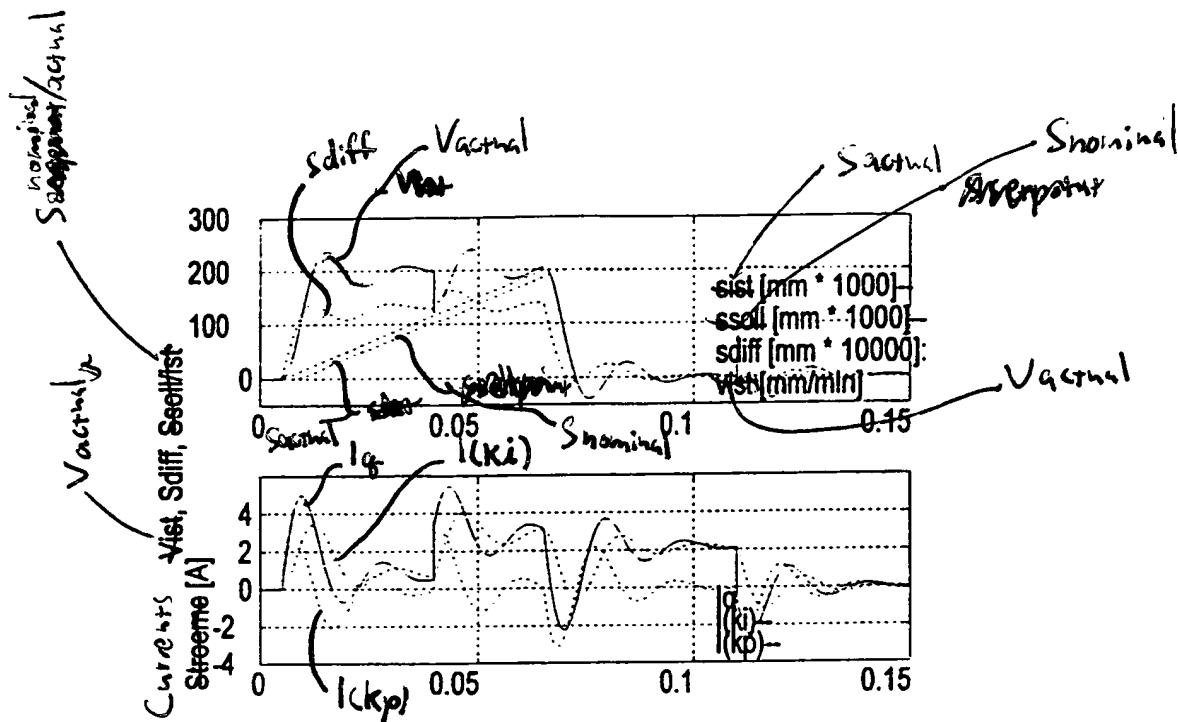
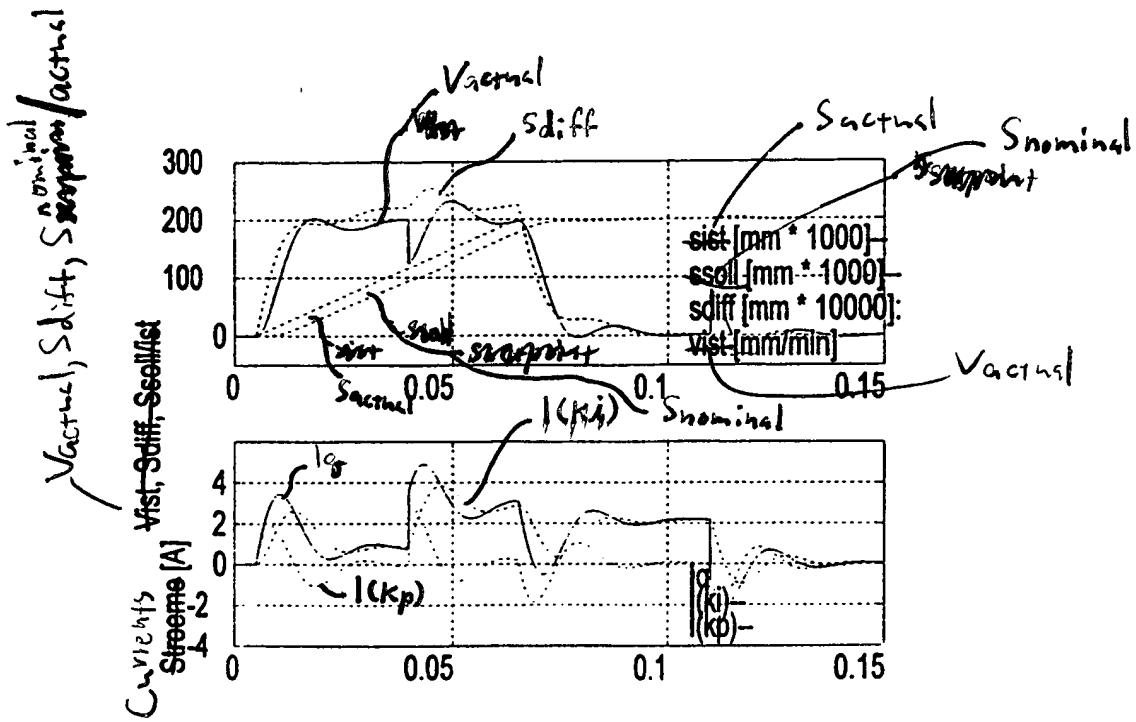


Fig. 9



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Fig. 10

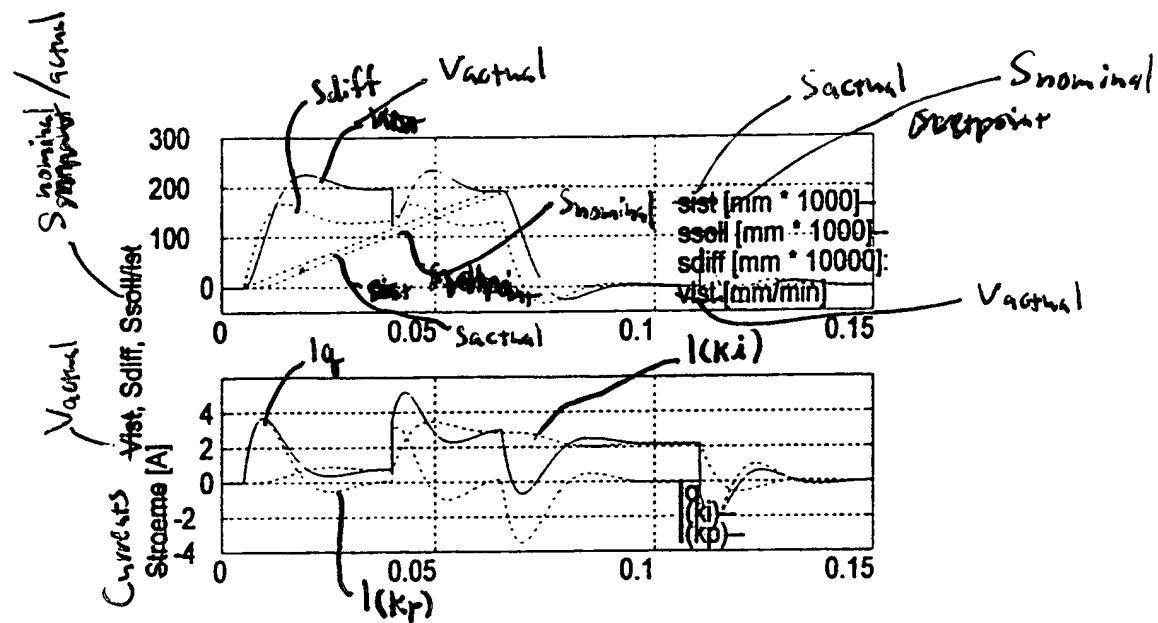
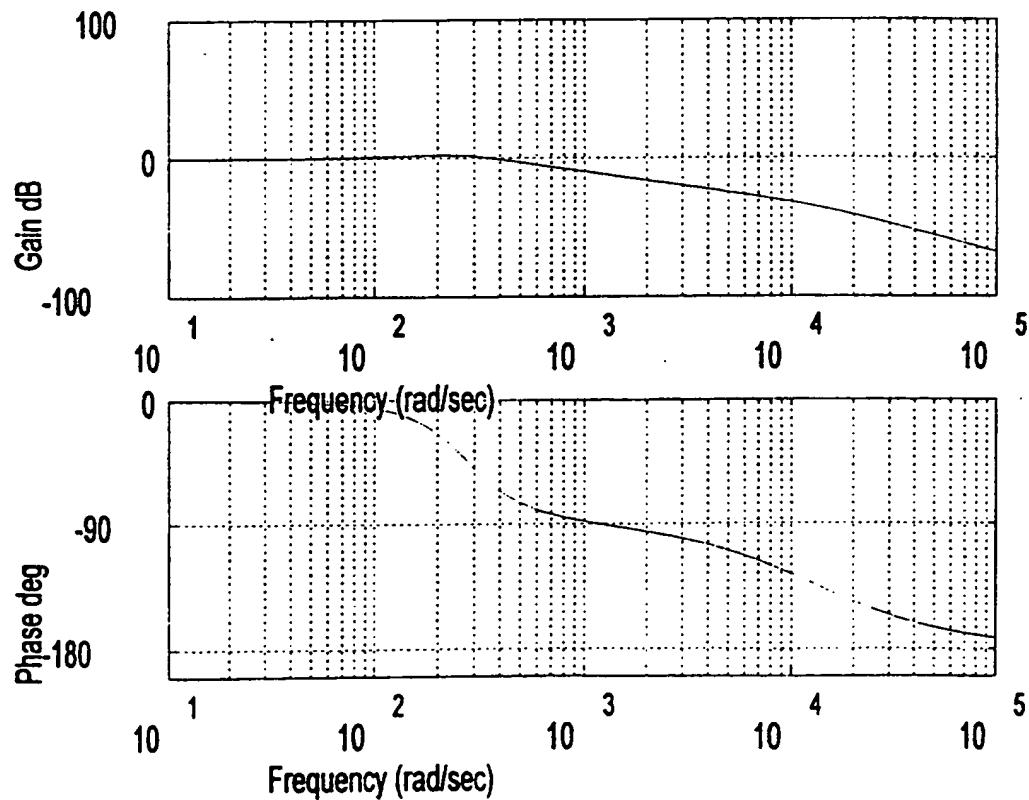
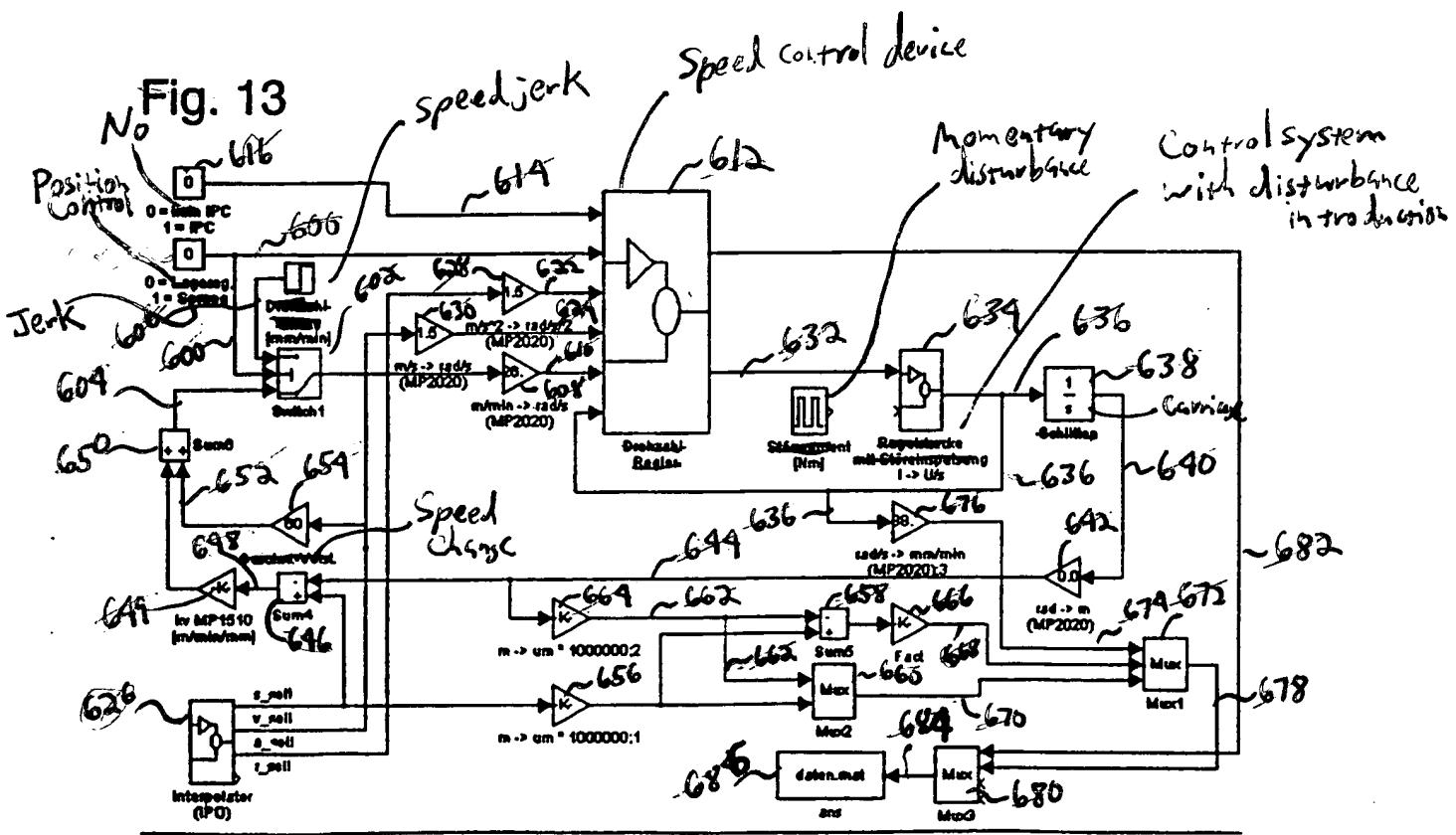
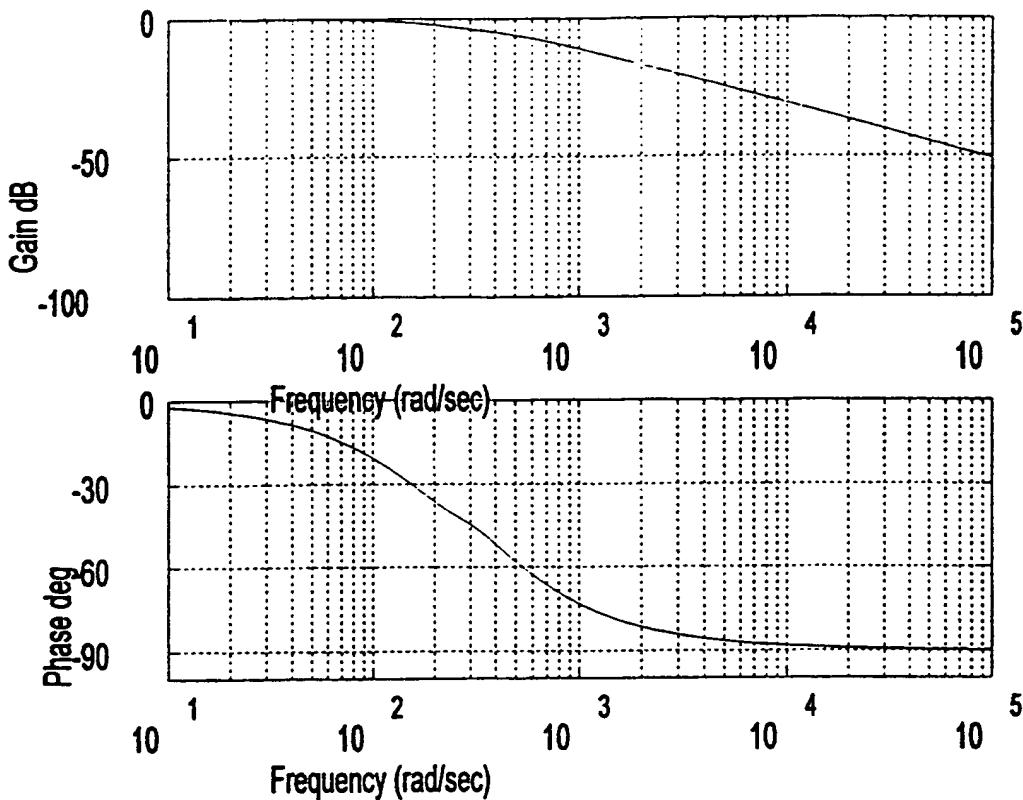


Fig. 11



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Fig. 12



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Fig. 14

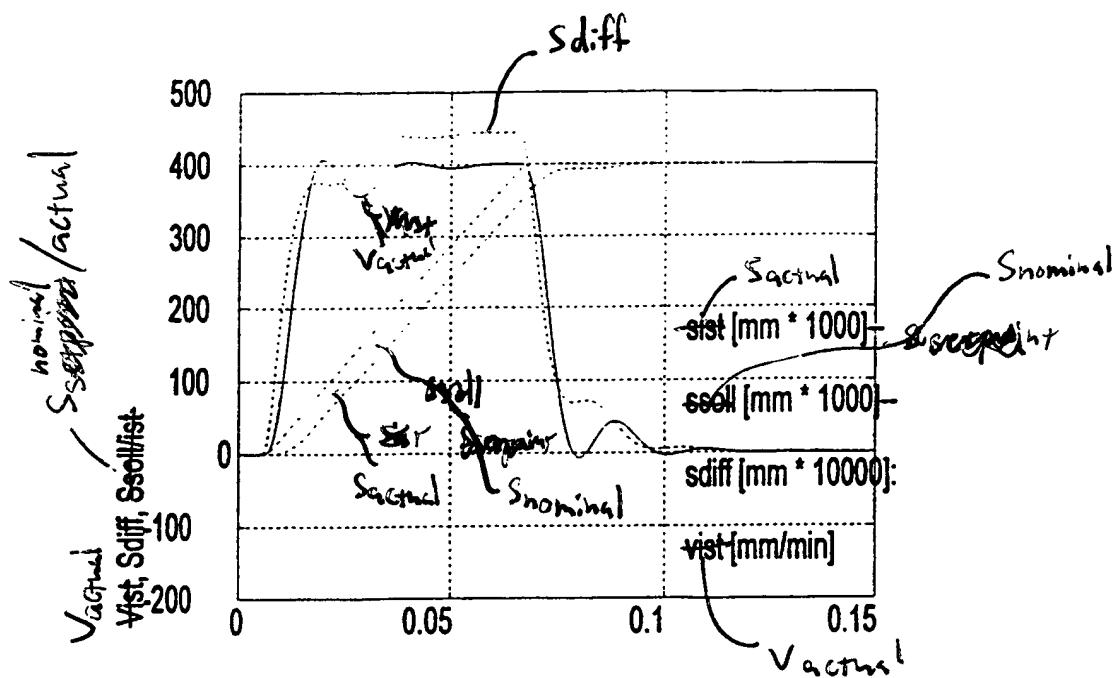
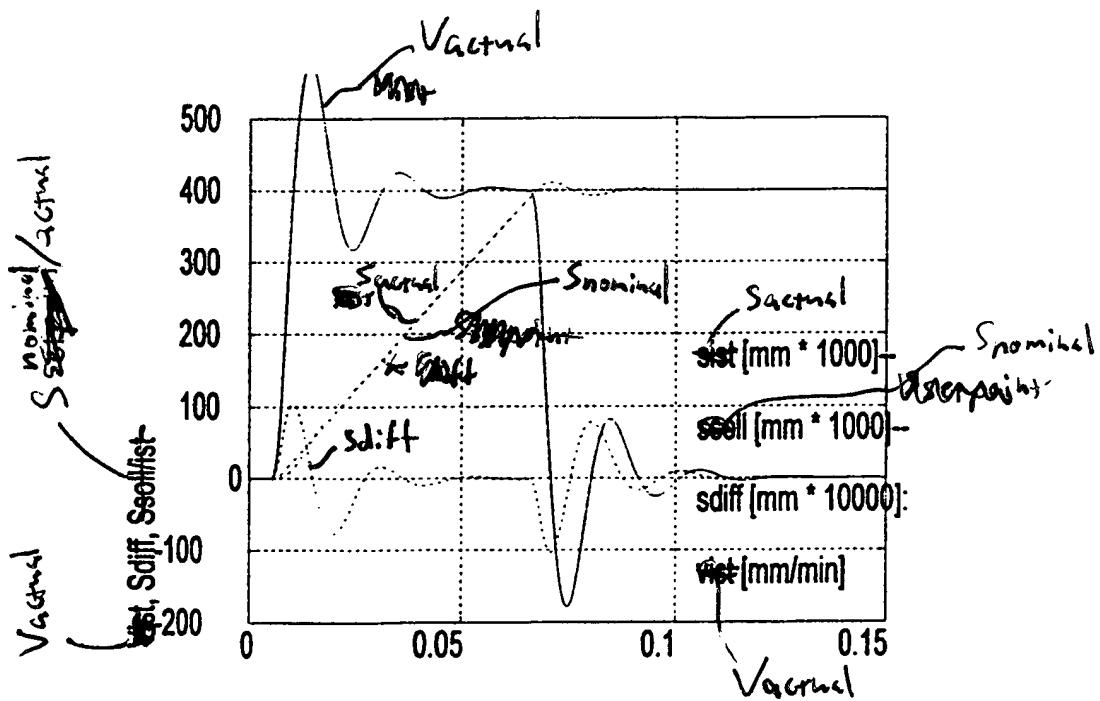


Fig. 15



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Fig. 16

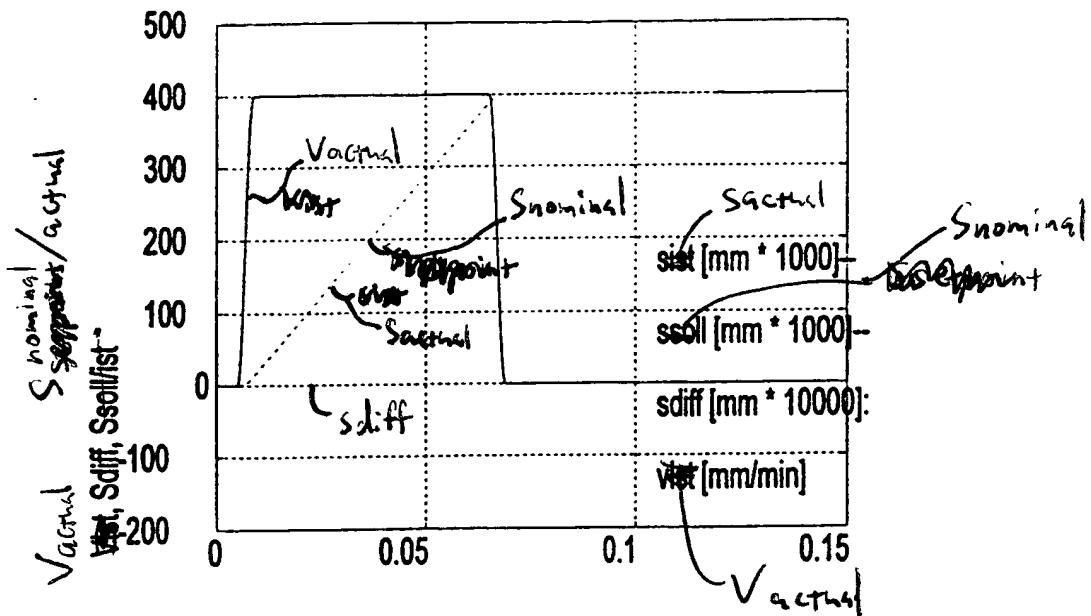


Fig. 17

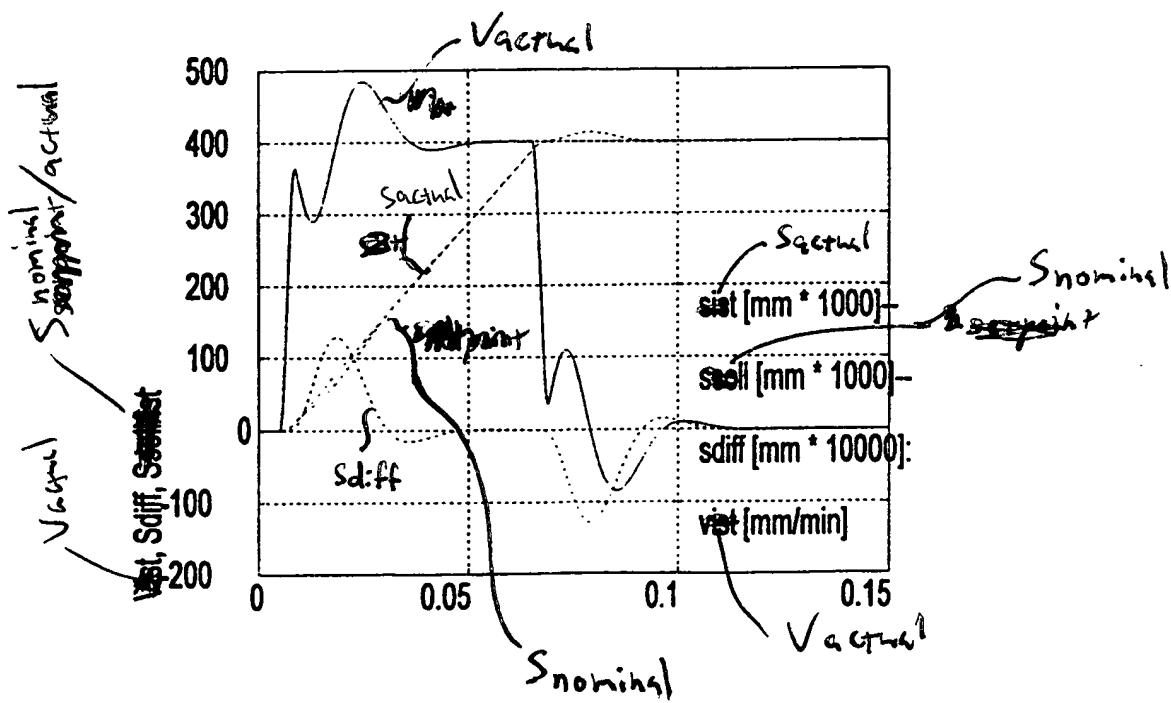


Fig. 18

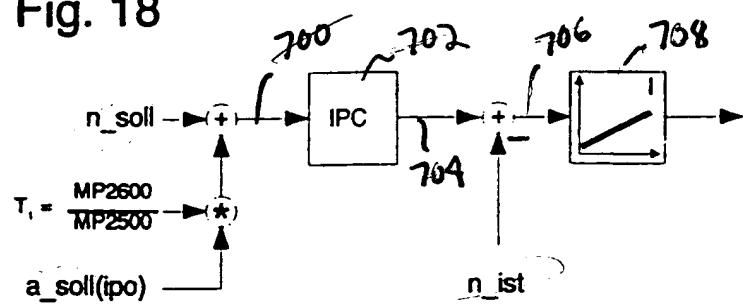


Fig. 19

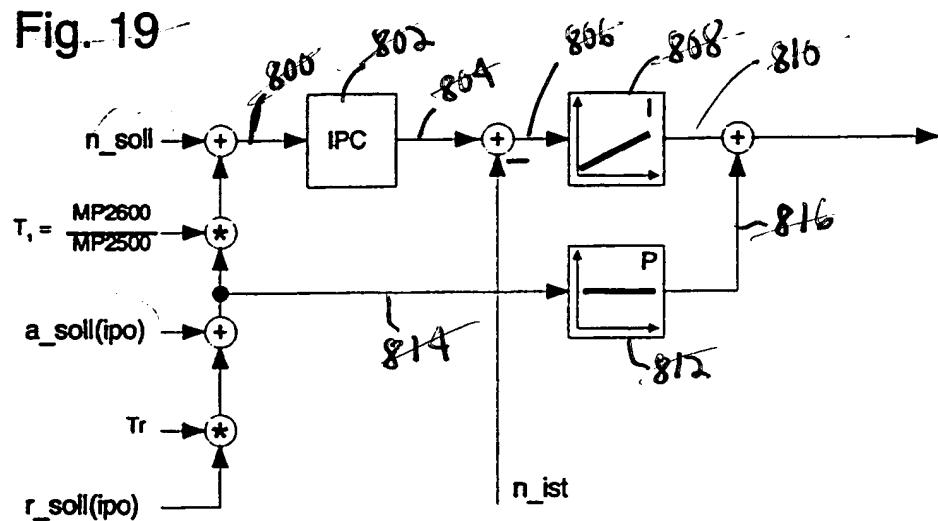


Fig. 20

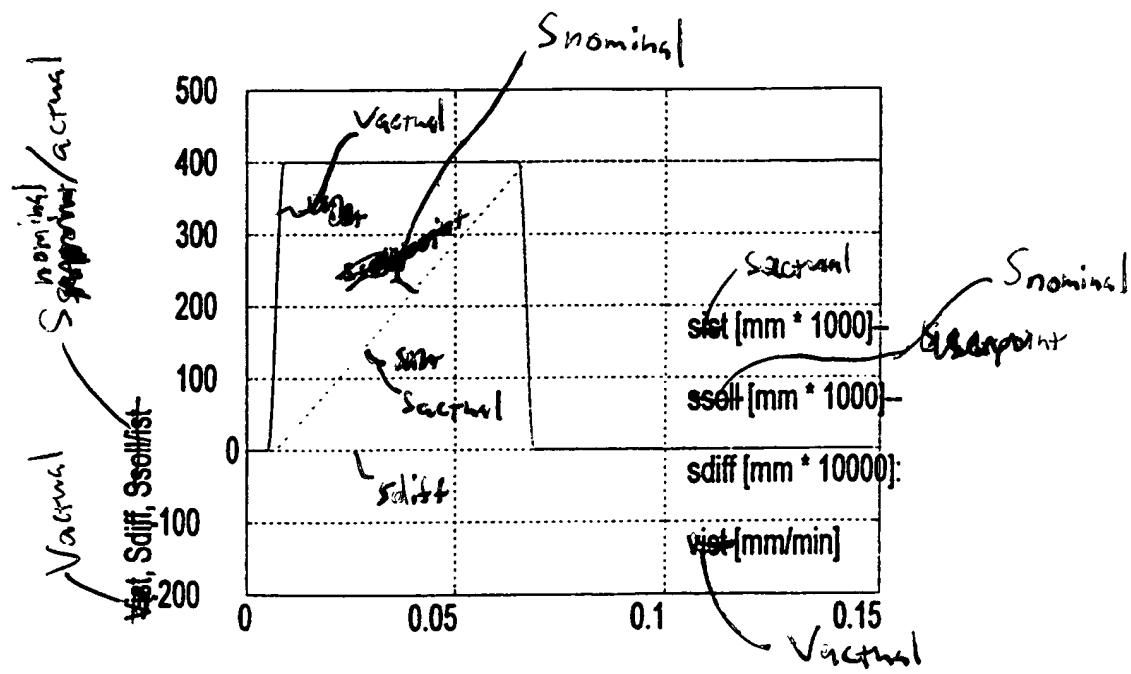


FIG. 21

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acceleration feedforward control

